SENSORS TRANSDUCERS

2 Vol. 10 Special 111







Sensors & Transducers

Volume 10, Special Issue, February 2011

www.sensorsportal.com

ISSN 1726-5479

Editors-in-Chief: professor Sergey Y. Yurish, tel.: +34 696067716, fax: +34 93 4011989, e-mail: editor@sensorsportal.com

Editors for Western Europe

Meijer, Gerard C.M., Delft University of Technology, The Netherlands Ferrari, Vittorio, Universitá di Brescia, Italy

Editor South America

Costa-Felix, Rodrigo, Inmetro, Brazil

Editor for Eastern Europe

Sachenko, Anatoly, Ternopil State Economic University, Ukraine

Editors for North America

Datskos, Panos G., Oak Ridge National Laboratory, USA Fabien, J. Josse, Marquette University, USA Katz, Evgeny, Clarkson University, USA

Editor for Asia

Ohyama, Shinji, Tokyo Institute of Technology, Japan

Editor for Asia-Pacific

Mukhopadhyay, Subhas, Massey University, New Zealand

Editorial Advisory Board

Abdul Rahim, Ruzairi, Universiti Teknologi, Malaysia

Ahmad, Mohd Noor, Nothern University of Engineering, Malaysia

Annamalai, Karthigeyan, National Institute of Advanced Industrial Science and Technology, Japan

Arcega, Francisco, University of Zaragoza, Spain

Arguel, Philippe, CNRS, France

Ahn, Jae-Pyoung, Korea Institute of Science and Technology, Korea

Arndt, Michael, Robert Bosch GmbH, Germany Ascoli, Giorgio, George Mason University, USA Atalay, Selcuk, Inonu University, Turkey

Atghiaee, Ahmad, University of Tehran, Iran

Augutis, Vygantas, Kaunas University of Technology, Lithuania Avachit, Patil Lalchand, North Maharashtra University, India

Ayesh, Aladdin, De Montfort University, UK

Bahreyni, Behraad, University of Manitoba, Canada Baliga, Shankar, B., General Monitors Transnational, USA

Baoxian, Ye, Zhengzhou University, China Barford, Lee, Agilent Laboratories, USA Barlingay, Ravindra, RF Arrays Systems, India

Basu, Sukumar, Jadavpur University, India **Beck, Stephen,** University of Sheffield, UK

Ben Bouzid, Sihem, Institut National de Recherche Scientifique, Tunisia

Benachaiba, Chellali, Universitaire de Bechar, Algeria

Binnie, T. David, Napier University, UK

Bischoff, Gerlinde, Inst. Analytical Chemistry, Germany

Bodas, Dhananjay, IMTEK, Germany

Borges Carval, Nuno, Universidade de Aveiro, Portugal Bousbia-Salah, Mounir, University of Annaba, Algeria

Bouvet, Marcel, CNRS - UPMC, France

Brudzewski, Kazimierz, Warsaw University of Technology, Poland

Cai, Chenxin, Nanjing Normal University, China
Cai, Qingyun, Hunan University, China
Campanella, Luigi, University La Sapienza, Italy
Carvalho, Vitor, Minho University, Portugal
Cecelja, Franjo, Brunel University, London, UK
Cerda Belmonte, Judith, Imperial College London, UK

Chakrabarty, Chandan Kumar, Universiti Tenaga Nasional, Malaysia Chakravorty, Dipankar, Association for the Cultivation of Science, India

Changhai, Ru, Harbin Engineering University, China Chaudhari, Gajanan, Shri Shivaji Science College, India

Chavali, Murthy, N.I. Center for Higher Education, (N.I. University), India

Chen, Jiming, Zhejiang University, China

Chen, Rongshun, National Tsing Hua University, Taiwan Cheng, Kuo-Sheng, National Cheng Kung University, Taiwan

Chiang, Jeffrey (Cheng-Ta), Industrial Technol. Research Institute, Taiwan

Chiriac, Horia, National Institute of Research and Development, Romania

Chowdhuri, Arijit, University of Delhi, India

Chung, Wen-Yaw, Chung Yuan Christian University, Taiwan Corres, Jesus, Universidad Publica de Navarra, Spain

Cortes, Camilo A., Universidad Nacional de Colombia, Colombia

Courtois, Christian, Universite de Valenciennes, France

Cusano, Andrea, University of Sannio, Italy D'Amico, Arnaldo, Università di Tor Vergata, Italy

De Stefano, Luca, Institute for Microelectronics and Microsystem, Italy

Deshmukh, Kiran, Shri Shivaji Mahavidyalaya, Barshi, India

Dickert, Franz L., Vienna University, Austria Dieguez, Angel, University of Barcelona, Spain Dimitropoulos, Panos, University of Thessaly, Greece

Ding, Jianning, Jiangsu Polytechnic University, China

Djordjevich, Alexandar, City University of Hong Kong, Hong Kong **Donato, Nicola,** University of Messina, Italy

Donato, Patricio, Universidad de Mar del Plata, Argentina

Dong, Feng, Tianjin University, China

Drljaca, Predrag, Instersema Sensoric SA, Switzerland

Dubey, Venketesh, Bournemouth University, UK

Enderle, Stefan, Univ.of Ulm and KTB Mechatronics GmbH, Germany

Erdem, Gursan K. Arzum, Ege University, Turkey

Erkmen, Aydan M., Middle East Technical University, Turkey

Estelle, Patrice, Insa Rennes, France

Estrada, Horacio, University of North Carolina, USA

Faiz, Adil, INSA Lyon, France

Fericean, Sorin, Balluff GmbH, Germany

Fernandes, Joana M., University of Porto, Portugal

Francioso, Luca, CNR-IMM Institute for Microelectronics and Microsystems, Italy

Francis, Laurent, University Catholique de Louvain, Belgium

Fu, Weiling, South-Western Hospital, Chongqing, China

Gaura, Elena, Coventry University, UK

Geng, Yanfeng, China University of Petroleum, China Gole, James, Georgia Institute of Technology, USA Gong, Hao, National University of Singapore, Singapore Gonzalez de la Rosa, Juan Jose, University of Cadiz, Spain

Granel, Annette, Goteborg University, Sweden

Graff, Mason, The University of Texas at Arlington, USA **Guan, Shan,** Eastman Kodak, USA

Guillet, Bruno, University of Caen, France Guo, Zhen, New Jersey Institute of Technology, USA Gupta, Narendra Kumar, Napier University, UK Hadjiloucas, Sillas, The University of Reading, UK Haider, Mohammad R., Sonoma State University, USA Hashsham, Syed, Michigan State University, USA

Hasni, Abdelhafid, Bechar University, Algeria Hernandez, Alvaro, University of Alcala, Spain

Hernandez, Wilmar, Universidad Politecnica de Madrid, Spain

Homentcovschi, Dorel, SUNY Binghamton, USA Horstman, Tom, U.S. Automation Group, LLC, USA Hsiai, Tzung (John), University of Southern California, USA Huang, Jeng-Sheng, Chung Yuan Christian University, Taiwan

Huang, Star, National Tsing Hua University, Taiwan

Huang, Wei, PSG Design Center, USA

Hui, David, University of New Orleans, USA

Jaffrezic-Renault, Nicole, Ecole Centrale de Lyon, France Jaime Calvo-Galleg, Jaime, Universidad de Salamanca, Spain

James, Daniel, Griffith University, Australia

Janting, Jakob, DELTA Danish Electronics, Denmark Jiang, Liudi, University of Southampton, UK

Jiang, Wei, University of Virginia, USA Jiao, Zheng, Shanghai University, China

John, Joachim, IMEC, Belgium

Kalach, Andrew, Voronezh Institute of Ministry of Interior, Russia

Kang, Moonho, Sunmoon University, Korea South

Kaniusas, Eugenijus, Vienna University of Technology, Austria

Katake, Anup, Texas A&M University, USA Kausel, Wilfried, University of Music, Vienna, Austria

Kavasoglu, Nese, Mugla University, Turkey Ke, Cathy, Tyndall National Institute, Ireland Khelfaoui, Rachid, Université de Bechar, Algeria Khan, Asif, Aligarh Muslim University, Aligarh, India

Kim, Min Young, Kyungpook National University, Korea South

Ko, Sang Choon, Electronics. and Telecom. Research Inst., Korea South

Kockar, Hakan, Balikesir University, Turkey

Kotulska, Malgorzata, Wroclaw University of Technology, Poland

Kratz, Henrik, Uppsala University, Sweden Kumar, Arun, University of South Florida, USA Kumar, Subodh, National Physical Laboratory, India

Kung, Chih-Hsien, Chang-Jung Christian University, Taiwan Lacnjevac, Caslav, University of Belgrade, Serbia Lay-Ekuakille, Aime, University of Lecce, Italy Lee, Jang Myung, Pusan National University, Korea South Lee, Jun Su, Amkor Technology, Inc. South Korea Lei, Hua, National Starch and Chemical Company, USA Li, Genxi, Nanjing University, China Li, Hui, Shanghai Jiaotong University, China Li, Xian-Fang, Central South University, China Liang, Yuanchang, University of Washington, USA Liawruangrath, Saisunee, Chiang Mai University, Thailand Liew, Kim Meow, City University of Hong Kong, Hong Kong Lin, Hermann, National Kaohsiung University, Taiwan Lin, Paul, Cleveland State University, USA Linderholm, Pontus, EPFL - Microsystems Laboratory, Switzerland Liu, Aihua, University of Oklahoma, USA Liu Changgeng, Louisiana State University, USA Liu, Cheng-Hsien, National Tsing Hua University, Taiwan Liu, Songqin, Southeast University, China Lodeiro, Carlos, University of Vigo, Spain Lorenzo, Maria Encarnacio, Universidad Autonoma de Madrid, Spain Lukaszewicz, Jerzy Pawel, Nicholas Copernicus University, Poland Ma, Zhanfang, Northeast Normal University, China Majstorovic, Vidosav, University of Belgrade, Serbia Marquez, Alfredo, Centro de Investigacion en Materiales Avanzados, Mexico Matay, Ladislav, Slovak Academy of Sciences, Slovakia Mathur, Prafull, National Physical Laboratory, India Maurya, D.K., Institute of Materials Research and Engineering, Singapore Mekid, Samir, University of Manchester, UK Melnyk, Ivan, Photon Control Inc., Canada Mendes, Paulo, University of Minho, Portugal Mennell, Julie, Northumbria University, UK Mi, Bin, Boston Scientific Corporation, USA Minas, Graca, University of Minho, Portugal Moghavvemi, Mahmoud, University of Malaya, Malaysia Mohammadi, Mohammad-Reza, University of Cambridge, UK Molina Flores, Esteban, Benemérita Universidad Autónoma de Puebla, Mexico Moradi, Majid, University of Kerman, Iran Morello, Rosario, University "Mediterranea" of Reggio Calabria, Italy Mounir, Ben Ali, University of Sousse, Tunisia Mulla, Imtiaz Sirajuddin, National Chemical Laboratory, Pune, India Nabok, Aleksey, Sheffield Hallam University, UK Neelamegam, Periasamy, Sastra Deemed University, India Neshkova, Milka, Bulgarian Academy of Sciences, Bulgaria Oberhammer, Joachim, Royal Institute of Technology, Sweden Ould Lahoucine, Cherif, University of Guelma, Algeria Pamidighanta, Sayanu, Bharat Electronics Limited (BEL), India Penza, Michele, ENEA C.R., Italy Pereira, Jose Miguel, Instituto Politecnico de Setebal, Portugal Petsev, Dimiter, University of New Mexico, USA Pogacnik, Lea, University of Ljubljana, Slovenia Post, Michael, National Research Council, Canada

Pan, Jisheng, Institute of Materials Research & Engineering, Singapore Park, Joon-Shik, Korea Electronics Technology Institute, Korea South

Prance, Robert, University of Sussex, UK Prasad, Ambika, Gulbarga University, India Prateepasen, Asa, Kingmoungut's University of Technology, Thailand

Pullini, Daniele, Centro Ricerche FIAT, Italy

Pumera, Martin, National Institute for Materials Science, Japan Radhakrishnan, S. National Chemical Laboratory, Pune, India

Rajanna, K., Indian Institute of Science, India

Ramadan, Qasem, Institute of Microelectronics, Singapore Rao, Basuthkar, Tata Inst. of Fundamental Research, India

Raoof, Kosai, Joseph Fourier University of Grenoble, France Reig, Candid, University of Valencia, Spain

Restivo, Maria Teresa, University of Porto, Portugal

Robert, Michel, University Henri Poincare, France Rezazadeh, Ghader, Urmia University, Iran

Royo, Santiago, Universitat Politecnica de Catalunya, Spain

Rodriguez, Angel, Universidad Politecnica de Cataluna, Spain Rothberg, Steve, Loughborough University, UK

Sadana, Ajit, University of Mississippi, USA Sadeghian Marnani, Hamed, TU Delft, The Netherlands

Sandacci, Serghei, Sensor Technology Ltd., UK Schneider, John K., Ultra-Scan Corporation, USA Sengupta, Deepak, Advance Bio-Photonics, India

Shah, Kriyang, La Trobe University, Australia

Sapozhnikova, Ksenia, D.I.Mendeleyev Institute for Metrology, Russia Saxena, Vibha, Bhbha Atomic Research Centre, Mumbai, India

Seif, Selemani, Alabama A & M University, USA Seifter, Achim, Los Alamos National Laboratory, USA Silva Girao, Pedro, Technical University of Lisbon, Portugal

Singh, V. R., National Physical Laboratory, India

Slomovitz, Daniel, UTE, Uruguay Smith, Martin, Open University, UK

Soleymanpour, Ahmad, Damghan Basic Science University, Iran Somani, Prakash R., Centre for Materials for Electronics Technol., India

Srinivas, Talabattula, Indian Institute of Science, Bangalore, India

Srivastava, Arvind K., NanoSonix Inc., USA

Stefan-van Staden, Raluca-Ioana, University of Pretoria, South Africa Sumriddetchka, Sarun, National Electronics and Computer Technology Center, Thailand

Sun, Chengliang, Polytechnic University, Hong-Kong

Sun, Dongming, Jilin University, China

Sun, Junhua, Beijing University of Aeronautics and Astronautics, China

Sun, Zhiqiang, Central South University, China

Suri, C. Raman, Institute of Microbial Technology, India Sysoev, Victor, Saratov State Technical University, Russia

Szewczyk, Roman, Industrial Research Inst. for Automation and Measurement,

Poland

Tan, Ooi Kiang, Nanyang Technological University, Singapore,

Tang, Dianping, Southwest University, China

Tang, Jaw-Luen, National Chung Cheng University, Taiwan Teker, Kasif, Frostburg State University, USA

Thirunavukkarasu, I., Manipal University Karnataka, India

Thumbavanam Pad, Kartik, Carnegie Mellon University, USA

Tian, Gui Yun, University of Newcastle, UK

Tsiantos, Vassilios, Technological Educational Institute of Kaval, Greece

Tsigara, Anna, National Hellenic Research Foundation, Greece

Twomey, Karen, University College Cork, Ireland

Valente, Antonio, University, Vila Real, - U.T.A.D., Portugal

Vanga, Raghav Rao, Summit Technology Services, Inc., USA

Vaseashta, Ashok, Marshall University, USA

Vazquez, Carmen, Carlos III University in Madrid, Spain

Vieira, Manuela, Instituto Superior de Engenharia de Lisboa, Portugal

Vigna, Benedetto, STMicroelectronics, Italy

Vrba, Radimir, Brno University of Technology, Czech Republic

Wandelt, Barbara, Technical University of Lodz, Poland

Wang, Jiangping, Xi'an Shiyou University, China

Wang, Kedong, Beihang University, China

Wang, Liang, Pacific Northwest National Laboratory, USA

Wang, Mi, University of Leeds, UK

Wang, Shinn-Fwu, Ching Yun University, Taiwan

Wang, Wei-Chih, University of Washington, USA

Wang, Wensheng, University of Pennsylvania, USA

Watson, Steven, Center for NanoSpace Technologies Inc., USA

Weiping, Yan, Dalian University of Technology, China Wells, Stephen, Southern Company Services, USA

Wolkenberg, Andrzej, Institute of Electron Technology, Poland

Woods, R. Clive, Louisiana State University, USA

Wu, DerHo, National Pingtung Univ. of Science and Technology, Taiwan

Wu, Zhaoyang, Hunan University, China

Xiu Tao, Ge, Chuzhou University, China

Xu, Lisheng, The Chinese University of Hong Kong, Hong Kong

Xu, Sen, Drexel University, USA

Xu, Tao, University of California, Irvine, USA Yang, Dongfang, National Research Council, Canada

Yang, Shuang-Hua, Loughborough University, UK

Yang, Wuqiang, The University of Manchester, UK

Yang, Xiaoling, University of Georgia, Athens, GA, USA

Yaping Dan, Harvard University, USA

Ymeti, Aurel, University of Twente, Netherland

Yong Zhao, Northeastern University, China

Yu, Haihu, Wuhan University of Technology, China

Yuan, Yong, Massey University, New Zealand

Yufera Garcia, Alberto, Seville University, Spain

Zakaria, Zulkarnay, University Malaysia Perlis, Malaysia

Zagnoni, Michele, University of Southampton, UK

Zamani, Cyrus, Universitat de Barcelona, Spain

Zeni, Luigi, Second University of Naples, Italy

Zhang, Minglong, Shanghai University, China

Zhang, Qintao, University of California at Berkeley, USA

Zhang, Weiping, Shanghai Jiao Tong University, China

Zhang, Wenming, Shanghai Jiao Tong University, China

Zhang, Xueji, World Precision Instruments, Inc., USA

Zhong, Haoxiang, Henan Normal University, China

Zhu, Qing, Fujifilm Dimatix, Inc., USA

Zorzano, Luis, Universidad de La Rioja, Spain

Zourob, Mohammed, University of Cambridge, UK



Contents

Volume 10 Special Issue February 2011

www.sensorsportal.com

ISSN 1726-5479

Research Articles

Research Articles	
Foreword Sergey Y. Yurish, Petre Dini	1
Film-based Sensors with Piezoresistive Molecular Conductors as Active Components: Strain Damage and Thermal Regeneration	
Elena Laukhina, Raphael Pfattner, Marta Mas-Torrent, Concepcio´ Rovira, Jaume Veciana, Vladimir Laukhin	1
Intelligent Sensor for Non-destructive Tests Applications Irinela Chilibon	10
Sensor Devices with Metrological Self-Check Roald Taymanov, Ksenia Sapozhnikova, Igor Druzhinin	30
A Simple and Universal Resistive-Bridge Sensors Interface Sergey Y. Yurish	46
Charge-sensitive Infrared Phototransisotrs: Single-photon Detctors in the Long- Wavelength Infrared Takeji Ueda and Susumu Komiyama	60
In the Field Application of a New Sensor for Monitoring Road and Runway Surfaces Amedeo Troiano, Eros Pasero, Luca Mesin	7
A New Concept for an Effective Leak Detection and Loclisation in Multiphase Fluid Pipelines Mahmoud Meribout	8
Double Pin Photodiodes with Two Optical Gate Connections for Light Triggering: A Capacitive Two-phototransistor Model	
Manuel A. Vieira, Manuela Vieira, João Costa, Paula Louro, Miguel Fernandes, A. Fantoni	9
Methane Detection by Nano ZnO Based MIM Sensor Devices P. Bhattacharyya, P. K. Basu, S. Basu	12
Detection of Hydrogen by Noble Metal Treated Nanoporous Si and ZnO Thin Films Jayita Kanungo, Palash Kumar Basu, Anita Lloyd Spetz, Sukumar Basu	13
Fabrication and Characterization of Ethanol Sensor Based on RF Sputtered ITO Films H. J. Pandya, Sudhir Chandra and A. L. Vyas	14
Performances of Three Miniature Bio-inspired Optic Flow Sensors under Natural Conditions	
Stéphane Viollet, Franck Ruffier, Thomas Ray, Lubin Kerhuel, Fabrice Aubépart, Nicolas Franceschini, Mohsine Ménouni	15

Generation of HDL Models for Bio-Impedance Sensor Simulation based on Microelectrodes Alberto Yúfera, Estefanía Gallego			
Design of Networked Low-Cost Wireless Noise Measurement Sensor Ilkka Kivelä, Chao Gao, Jari Luomala, Jukka Ihalainen, Ismo Hakala	171		
Fast FPGA Implementation of an Original Impedance Analyser Abdulrahman Hamed, Etienne Tisserand, Yves Berviller, Patrick Schweitzer	191		
Experimental and Computational Performance Analysis of a Multi-Sensor Wireless Network System for Hurricane Monitoring Chelakara Subramanian, Gabriel Lapilli, Frederic Kreit, Jean-Paul Pinelli, Ivica Kostanic	206		

Authors are encouraged to submit article in MS Word (doc) and Acrobat (pdf) formats by e-mail: editor@sensorsportal.com Please visit journal's webpage with preparation instructions: http://www.sensorsportal.com/HTML/DIGEST/Submition.htm

International Frequency Sensor Association (IFSA).

Call for Books Proposals

Sensors, MEMS, Measuring instrumentation, etc.

International Frequency Sensor Association Publishing



Benefits and rewards of being an IFSA author:

1) Royalties.

Today IFSA offers most high royalty in the world: you will receive 50 % of each book sold in comparison with 8-11 % from other publishers, and get payment on monthly basis compared with other publishers' yearly basis.

2) Quick Publication.

IFSA recognizes the value to our customers of timely information, so we produce your book quickly: 2 months publishing schedule compared with other publishers' 5-18-month schedule.

3) The Best Targeted Marketing and Promotion.

As a leading online publisher in sensors related fields, IFSA and its Sensors Web Portal has a great expertise and experience to market and promote your book worldwide. An extensive marketing plan will be developed for each new book, including intensive promotions in IFSA's media: journal, magazine, newsletter and online bookstore at Sensors Web Portal.

4) Published Format: pdf (Acrobat).

When you publish with IFSA your book will never go out of print and can be delivered to customers in a few minutes.

You are invited kindly to share in the benefits of being an IFSA author and to submit your book proposal or/and a sample chapter for review by e-mail to **editor@sensorsportal.com** These proposals may include technical references, application engineering handbooks, monographs, guides and textbooks. Also edited survey books, state-of-the art or state-of-the-technology, are of interest to us.





The Second International Conference on Sensor Device Technologies and Applications

SENSORDEVICES 2011

August 21-27, 2011 - French Riviera, France



Important deadlines:

Submission deadline March 23, 2011 Notification April 30, 2011 Registration May 15, 2011 May 22, 2011 Camera ready

Tracks:

- Sensor devices
- Photonics
- Infrared
- Ultrasonic and Piezosensors
- Sensor device technologies
- Sensors signal conditioning and interfacing circuits
- Medical devices and sensors applications
- Sensors domain-oriented devices, technologies, and applications
- Sensor-based localization and tracking technologies

http://www.iaria.org/conferences2011/SENSORDEVICES11.html



The Fifth International Conference on Sensor **Technologies and Applications**

SENSORCOMM 2011

August 21-27, 2011 - French Riviera, France



Important deadlines:

Submission deadline March 23, 2011 Notification April 30, 2011 Registration May 15, 2011 May 22, 2011 Camera ready

Tracks:

- APASN: Architectures, protocols and algorithms of sensor networks
- MECSN: Energy, management and control of sensor networks
- RASQOFT: Resource allocation, services, QoS and fault tolerance in sensor networks
- PESMOSN: Performance, simulation and modelling of sensor networks
- SEMOSN: Security and monitoring of sensor networks
- SECSED: Sensor circuits and sensor devices
- RIWISN: Radio issues in wireless sensor networks
- SAPSN: Software, applications and programming of sensor networks - DAIPSN: Data allocation and information in sensor networks
- DISN: Deployments and implementations of sensor networks
- UNWAT: Under water sensors and systems
- ENOPT: Energy optimization in wireless sensor networks

http://www.iaria.org/conferences2011/SENSORCOMM11.html



The Fourth International Conference on Advances in Circuits, Electronics and Micro-electronics

CENICS 2011

August 21-27, 2011 - French Riviera, France



Important deadlines:

Submission deadline March 23, 2011 Notification April 30, 2011 Registration May 15, 2011 Camera ready May 22, 2011

- Semiconductors and applications
- Design, models and languages
- Signal processing circuits
- Arithmetic computational circuits
- Microelectronics
- Electronics technologies
- Special circuits
- Consumer electronics
- Application-oriented electronics

http://www.iaria.org/conferences2011/CENICS11.html









Sensors & Transducers

ISSN 1726-5479 © 2011 by IFSA http://www.sensorsportal.com

Performances of Three Miniature Bio-inspired Optic Flow Sensors under Natural Conditions

¹Stéphane Viollet, ¹Franck Ruffier, ¹Thomas Ray, ¹Lubin Kerhuel, ¹Fabrice Aubépart, ¹Nicolas Franceschini, ²Mohsine Ménouni

¹Institute of Movement Sciences - Biorobotics - CP938 - 163 av Luminy F-13288 Marseille, France ²Center for Particle Physics (CPPM) - CP902 - 163 av Luminy F-13288 Marseille, France

Received: 29 October 2010 /Accepted: 11 January 2011 /Published: 8 February 2011

Abstract: Considerable attention has been paid during the last decade to vision-based navigation systems based on optic flow (OF) cues. OF-based systems have been implemented on an increasingly large number of sighted autonomous robotic platforms. Nowadays, the OF is measured using conventional cameras, custom-made sensors and even optical mouse chips. However, very few studies have dealt so far with the reliability of these OF sensors in terms of their precision, range and sensitivity to illuminance variations. Three miniature custom-made OF sensors developed at our laboratory, which were composed of photosensors connected to an OF processing unit were tested and compared in this study, focusing on their responses and characteristics in real indoor and outdoor environments in a large range of illuminance. It was concluded that by combining a custom-made aVLSI retina equipped with Adaptive Pixels for Insect-based Sensor (APIS) with a bio-inspired visual processing system, it is possible to obtain highly effective miniature sensors for measuring the OF under real environmental conditions. *Copyright* © 2011 IFSA.

Keywords: Bio-inspired optic flow sensor, vision-based navigation system, autonomous robotic platform, OF sensor, VLSI retina, bio-inspired visual processing system

1. Introduction

Several examples of embedded optic flow-based navigation systems have been developed during the last decade or so. As in their natural counterparts (flies, bees, etc.) where the optic flow (OF) provides vital cues, aerial robots are now being endowed with similar means of detecting and processing OF for obstacle avoidance purposes [1] [2] [3] [4], terrain following and landing [5] and wall following [6]. However, there exist very few robotic examples in which OF sensing has been successfully

implemented under real indoor [7] or outdoor conditions environment [8] [9] [4]. Many OF sensors have been developed using analog VLSI technology (e.g., [10] [11]), but their relatively complex and bulky peripheral electronics have often made it impossible to implement these aVLSI sensors onboard aerial robots. The authors of some recent studies mounted off-the-shelf mouse sensors onboard terrestrial [12] [13] and aerial robotic platforms [9] [4]. However, the performances of these systems in terms of their resolution, accuracy, invariance to illuminance and contrast have not been properly assessed so far, except in [4] where a static characteristic of a mouse sensor for OF measurement is given. In this study, it was therefore proposed to compare the output signals of three custom-made bioinspired OF sensors with a reference angular speed measured by a rate gyro. Our own OF sensors, which we have also called Elementary Motion Detectors (EMDs), process the OF by comparing the signals collected by adjacent photosensors [14][15][2]. A purely rotational optic flow was generated by rotating the various OF sensors placed in front of a natural indoor or outdoor scene while the reference angular speed was being recorded synchronously. By definition, the rotational optic flow is not affected by the distance to object. A description of the various OF sensors tested here is given in section II. Section III gives an account of the performance of these OF sensors placed in a real environment in a large range of illuminance.

2. Description of the OF Sensors

Our OF sensors are basically composed of a lens and two photosensors (photodiodes) placed behind the lens. Each photodiode's output signal is sent to an OF processing unit where a discrete version of an EMD circuit is running. An EMD is used here to assess the relative angular speed Ω of contrasting features in the environment (i.e., the optic flow). Our original EMD design [14][15][2] consists of an analog circuit producing an output signal that increases as the time lag Δt between its two inputs decreases. The output signal therefore increases with the angular speed Ω , i.e., with the OF. Like the fly's motion-detecting neurons from which it was originally inspired [16], our electronic analogue EMD reacts to both dark-to-light (ON) and light-to-dark (OFF) contrast transitions. The EMD-inspired signal processing steps implemented onboard the three OF sensors can be decomposed into 5 steps as follows:

- Step 1: Low-pass spatial filtering (which is achieved by defocusing the lens to obtain Gaussian blurring),
- Step 2: Band-pass temporal filtering to derivate the visual signals and to reduce the noise and interference (such as the 100-Hz interference originating from artificial lighting),
- Step 3: Thresholding for contrast detection,
- Step 4: Measuring the time lag Δt (travel time) between the thresholded signals,
- Step 5: Computing the OF by applying:

$$\Omega_{meas} = \frac{\Delta \varphi}{\Delta t} \tag{1}$$

The angles $\Delta \varphi$ and $\Delta \rho$, called interreceptor angle and acceptance angle, respectively, are adjusted by slightly defocusing the lens placed in front of the photodiodes. For each OF sensor, the angle $\Delta \varphi$ determines directly the cut-off frequency of the low-pass spatial filtering (step 1) whereas the angle $\Delta \varphi$ determines the measurement range of the OF Ω . For a given resolution (here 1ms) in the measurement of the time lag Δt , the smaller the angle $\Delta \varphi$, the smaller the OF range will be. In this study, three OF sensors based on the same principle but using different technologies were compared (see Fig. 1).

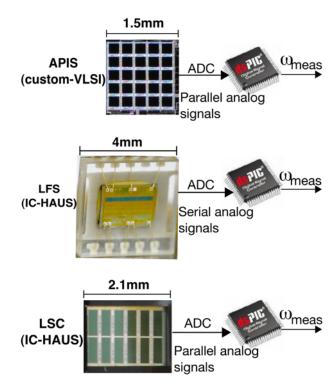


Fig. 1. General hardware architecture of the three OF sensors composed of a photodiodes array connected, via an analog-to-digital converter (ADC), to an external optic flow (OF) processing unit. The custom-made Adaptive Pixels for Insect-based Sensors (APIS) is made of 5x5 Delbrück-type [17] adaptive sensors. The off-the-shelf linear array (LFS and LSC from IC-HAUS) integrate amplifier circuits at the pixel level. For each sensor, the optic flow Ω_{meas} measured by each sensor is computed from the visual input signals provided by two adjacent pixels.

The first OF sensor, called APIS (Adaptive Pixels for Insect-based Sensor), is composed of a single lens (focal length 6.5mm) placed in front of a VLSI retina made of 2 adaptive pixels [17]. This retina was developed in collaboration with the Center for Particle Physics (CPPM, Marseille, France) [18]. The second OF sensor, called LSC, is composed of an optical assembly mounted onto an off-the-shelf photodiode array consisting of 6 pixels (IC-Haus, LSC). The LSC sensor was also endowed with an Automotic Gain Control (AGC) function implemented onboard the microcontroller. The third OF sensor, called LFS, is also composed of an optical assembly mounted in front of a 32 pixels linear imager (IC-Haus, LFS). The optic assemblies of the LSC and LFS sensors were simply borrowed from a low cost miniature camera (Velleman, focal length 4.9 mm) and a tiny CMOS color camera (CONRAD, focal length 2.2 mm), respectively. We used three different optics to make the ratio $\Delta \phi/\Delta \rho$ equal to 1. This ratio can be also found in several insects [19]. Table 1 summarizes the main characteristics of the OF sensors.

Table 1. Main characteristics of the OF sensors.

	APIS	LFS	LSC
Photodiode size (μm)	250×250	65×65	300×1600
Pixel pitch (μm)	300	63.5	420
F_{number}	1.1	1.4	2.8
Focal length (mm)	6.5	2.2	4.9
$\Delta ho(^\circ)$	3.41	0.83	7
$\Delta arphi(^\circ)$	3.2	0.83	7.3

Fig. 2 shows the three OF sensors mounted on a common printed circuit board. An additional illuminance sensor was connected to an analog amplifier running in the photovoltaic mode. The photocurrent I_{ph} of this illuminance sensor is obtained as follows [20]:

$$I_{ph} = \left(e^{\frac{V_{out}}{0.25}} - 1\right) I_{dark} , \qquad (2)$$

where the dark current I_{dark} is equal to 1nA and V_{out} is the amplifier's output voltage.

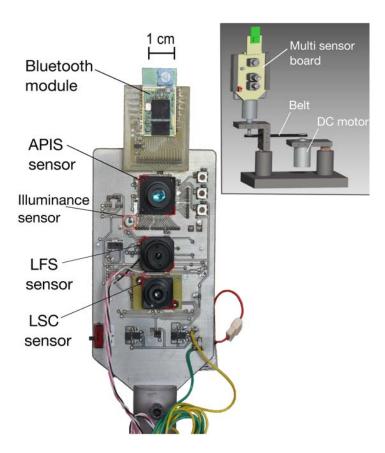


Fig. 2. The multi sensor PCB board includes three OF sensors, an illuminance sensor based on a single photodiode, a rate gyro for measuring the reference angular speed (i.e., the rotational speed of the board) and a microntroller (dSpic). The microcontroller processes the visual signals of all the three OF sensors at a sampling frequency of 1 kHz. The measured OF Ω_{meas} and the measured rotational speed Ω_{gyro} are recorded synchronously and sent to a computer through a Bluetooth module. The wireless link and the small onboard battery (LiPo, 300 mAh-3.3 V) made the multi sensor board free to rotate in complete autonomy on its two miniature ball-bearings. (Top right) A rotational speed was imposed on the board by means of a DC servomotor.

3. Experimental Results

As discussed in Section II, an optic flow sensor is an optical device that measures an angular speed Ω_{meas} . The three OF sensors were tested in indoor and outdoor environments (see Fig. 3) by comparing their output signals with respect to the angular speed Ω_{gyro} measured by a MEMS rate gyro with a maximum speed range of 300°/s. As shown in Fig. 2 (top right), the multi sensor board was coupled to a DC motor via a belt, which made it possible for the experimenter to adjust the rotational speed of the

board. The board was made to rotate at a rotational speed Ω varying sinusoidally within 60°/s to 300°/s range in the case of the APIS and LSC sensors and within the 60°/s to 200°/s range in that of the LFS sensor.



Fig. 3. Panoramic view of the real indoor (top) and outdoor (bottom) environments that were used to assess the OF sensor's responses.

3.1. Indoor Optic Flow Measurement

The response of the three OF sensors placed in the indoor environment is shown in Fig. 4. The measured optic flow Ω_{meas} (dark points) is superimposed on the measured reference angular speed Ω_{gyro} . Despite the strong 30-fold attenuated illuminance, the responses of the APIS and LSC sensors faithfully reflected the sinusoidal variation imposed by the mechanical rotation of the board. The response of the LFS was found to be noisier at high and very low illuminance levels due to the saturation of its output voltage and its lower sensitivity at the pixel level, respectively. The APIS and the LSC sensors were therefore selected for conducting further tests outdoors and for measuring their static characteristics.

3.2. Outdoor Optic Flow Measurement

Fig. 5 gives the responses of the two OF sensors placed in the outdoor environment. Although the illuminance was about 10-fold greater than the highest value of I_{ph} in the indoor environment, the dynamic outdoor responses of both the APIS and the LSC sensors followed the sinusoidal variations in the angular speed. The fact that a larger number of matching errors were observed in the case of the APIS sensor suggests that the specific optics used here (with a relatively large *f-number* of 1.1) was less well suited to the task in question than that of the LSC sensor (f-number of 2.8).

3.3. Static Characteristics of the OF Sensors

As shown in Fig. 6, the APIS sensor showed a high level of invariance to the illuminance while linearity of its static characteristics was well maintained. The static characteristics of the LSC sensor also showed a good linearity and a good invariance to the lighting conditions, provided the illuminance was maintained at a relatively high level.

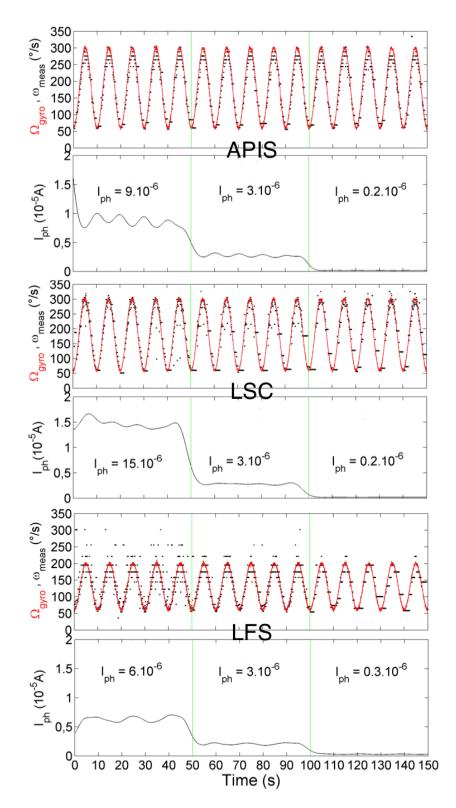


Fig. 4. Response profile of the three OF sensors to a sinusoidally changing rotational speed of the board on which they are mounted (cf. Fig. 2). The three OF sensors were placed in the *indoor* environment (Fig. 3) under three different lighting conditions. During the experiment, the mean value of the photodiode's current I_{ph} , i.e., the current measured by the illuminance sensor (red continuous line) was reduced stepwise over a range of up to 30-fold. Unlike the LFS sensor, the LSC with its AGC (cf. text) and the APIS sensor with its adaptive pixels showed a remarkable insensitivity to the illuminance.

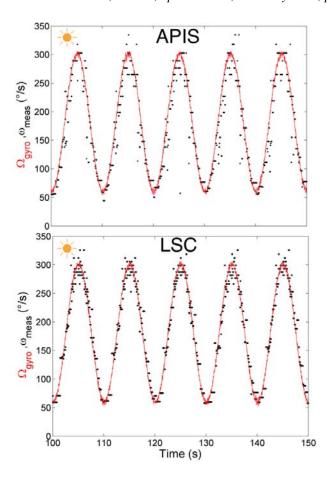


Fig. 5. Response of the LSC with its AGC and APIS sensors placed in the *outdoor* environment (Fig. 3). Despite the strong illuminance (which was 10 times higher than the maximum value of I_{ph} in the indoor environment), the two OF sensors faithfully followed the sine variation of the rotational angular speed.

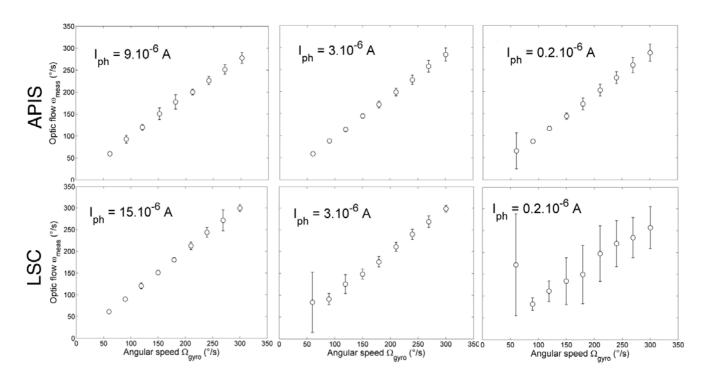


Fig. 6. Static characteristics of the LSC with its AGC and APIS sensors assessed by varying the rotational speed from 60° /s to 300° /s in 30° /s-steps. The different values of the average photocurrent I_{ph} given in this figure indicate that the illuminance of the indoor environment was attenuated by 30 dB.

4. Conclusion

Three OF sensors were tested here in real indoor and outdoor environments and under various lighting conditions. It turned out from the results of these tests that the APIS sensor based on a custom aVLSI retina equipped with adaptive pixels gave the best features in terms of invariance to the illuminance and precision. However, under outdoor conditions, the LSC sensor with its AGC made fewer matching errors (OF measurement errors) probably thanks to its better suited optics (smaller optical aperture, larger *f-number*). We therefore intend to modify the APIS optics to improve this sensor's dynamic responses in outdoor environments. To summarize, it was established here that OF sensors consisting of low cost optics and classical electronic components combined with appropriate visual signal processing methods can give accurate and reliable results under *natural conditions* (indoor or outdoor environments). This study brings us one step further towards implementing tiny, light and robust OF sensors that could invest many application fields as domestic, biomedical, automotive, robotic and aerospace sensors.

Acknowledgements

We are very grateful to M. Boyron for his involvement in the electronic design and to Y. Luparini. This work was supported by he French Defense Agency (DGA, 05 34 022), the National Research Agency (ANR RETINAE and EVA projects) and the European Commission via the CURVACE project. The project CURVACE acknowledges the financial support of the Future and Emerging Technologies (FET) program within the Seventh Framework Program for Research of the European Commission, under FET Open grant number: 237940.

References

- [1]. W. E. Green et P. Y. Oh, Optic-Flow-Based Collision Avoidance, *Robotics & Automation Magazine*, *IEEE*, Vol. 15, No. 1, Mar. 2008, pp. 96-103.
- [2]. N. Franceschini, F. Ruffier, J. Serres, et S. Viollet, Aerial vehicles, T. M. Lam, Éd. Vienna: *In-Tech*, 2009, pp. 747-770.
- [3]. M. Srinivasan, S. Thurrowgood, et D. Soccol, Competent vision and navigation systems, *IEEE Robotics & Automation Magazine*, Vol. 16, No. 3, Sep. 2009, pp. 59–71.
- [4]. A. Beyeler, J. Zufferey, et D. Floreano, Vision-based control of near-obstacle flight, *Autonomous Robots*, Vol. 27, No. 3, Oct. 2009, pp. 201–219.
- [5]. F. Ruffier et N. Franceschini, Optic flow regulation: the key to aircraft automatic guidance, *Robotics and Autonomous Systems*, Vol. 50, 2005, pp. 177-194.
- [6]. J. Serres, D. Dray, F. Ruffier, et N. Franceschini, A vision-based autopilot for a miniature air vehicle: joint speed control and lateral obstacle avoidance, *Autonomous Robots*, Vol. 25, No. 1, 2008, pp. 103–122.
- [7]. J. Zufferey et D. Floreano, Fly-inspired visual steering of an ultralight indoor aircraft, *IEEE Transactions on Robotics*, Vol. 22, 2006, pp. 137-146.
- [8]. M. Garratt et J. Chahl, Visual control of an autonomous Helicopter, in *Proceeding of American Institute of Aeronautics and Astronautics*, 2003.
- [9]. S. Griffiths, J. Saunders, A. Curtis, B. Barber, T. McLain, et R. Beard, Maximizing miniature aerial vehicles, *Robotics & Automation Magazine, IEEE*, Vol. 13, No. 3, Sep. 2006, pp. 34-43.
- [10].R. R. Harrison et C. Koch, A Robust Analog VLSI Motion Sensor Based on the Visual System of the Fly, *Autonomous Robots*, Vol. 7, No. 3, Nov. 1999, pp. 211–224.
- [11].R. Moeckel et S. Liu, Motion Detection Circuits for a Time-To-Travel Algorithm, in *Circuits and Systems*, 2007. ISCAS 2007. IEEE International Symposium on, 2007, pp. 3079-3082.
- [12].J. D. Jackson, D. W. Callahan, et J. Marstrander, A Rationale for the use of Optical Mice Chips for Economic and Accurate Vehicle Tracking, in *Proc. of the IEEE International Conference on Automation Science and Engineering CASE 2007*, 2007, pp. 939–944.
- [13].H. Dahmen, A. Millers, et H. A. Mallot, Flying insects and robots, D. Floreano, J. C. Zufferey,

- M. V. Srinivasan, et C. P. Ellington, Éd. Springer, 2009, pp. 115-126.
- [14].C. Blanes, Appareil visuel élémentaire pour la navigation à vue d'un robot mobile autonome., Master Thesis in Neurosciences, *Univ. of Marseille*, France, 1986.
- [15].F. Ruffier, S. Viollet, S. Amic, et N. Franceschini, Bio-inspired optical flow circuits for the visual guidance of Micro-Air Vehicles, in *Proc. of the IEEE Int. Symposium on Circuits and Systems (ISCAS)*, Vol. III, 2003, pp. 846-849.
- [16].N. Franceschini, A. Riehle, et A. L. Nestour, Directionally Selective Motion Detection by Insect Neurons, in Facets of vision, D. G. Stavenga, R. C. Hardie, Eds., *Springer*, Berlin, 1989, pp. 360-390.
- [17].T. Delbrück et C. A. Mead, Adaptive photoreceptor with wide dynamic range, in *Proc. of the IEEE International Symposium on Circuits and Systems ISCAS '94*, Vol. 4, 1994, pp. 339–342.
- [18].F. Aubépart, M. Menouni, T. Loubignac, B. Dinkelspieler, et N. Franceschini, Capteur de flux optique basé sur une rétine intégrée et un FPGA, in *Colloque Interdisciplinaire en Instrumentation*, 2007, pp. 508-520.
- [19].M. F. Land, Visual acuity in insects., Annu Rev Entomol, Vol. 42, 1997, pp. 147–177.
- [20].J. D. Riggs, Notes on Silicon Photodiode Detectors, *International Amateur-Professional Photoelectric Photometry Communications*, Vol. 14, Déc. 1983, pp. 30-44.

2011 Copyright ©, International Frequency Sensor Association (IFSA). All rights reserved. (http://www.sensorsportal.com)

CMOS Image Sensors Technologies & Markets - 2010 Report

Disruptive technologies are paving the way to the future of digital imaging industry!

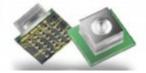
IFSA offers a SPECIAL PRICE

Image sensors have come a long way since the first introduction of CCD sensor technology in the 1990's. They made a big jump in the 2000's with the introduction of CMOS sensor technology which gave birth to the low-cost, high volume camera phone market. Image sensors are now part of our everyday life: from cell-phone cameras, to notebook webcams, digital cameras, video camcorders to security & surveillance systems. In the future, new markets are also emerging such as sensors for medical applications, automotive security features, but also gaming and home TV webcams ... The reason why we are now releasing our first report on the CMOS image sensor industry is that we feel that we are at an historic turning point for this young, but still maturing industry.

http://www.sensorsportal.com/HTML/CMOS_Image_Sensors.htm













Uncooled Infrared Cameras and Detectors
Thermography and Vision Markets
2010 - 2015

IFSA offers

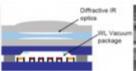
MEMS Micro-Bolometers Drive Growth

This report provides market data on both camera and detector; IR camera supply chain levels and main technological trends for detector/microbolometer.

http://www.sensorsportal.com/HTML/Detectors_for_Thermography.htm















a SPECIAL PRICE

Sensors & Transducers Journal



Guide for Contributors

Aims and Scope

Sensors & Transducers Journal (ISSN 1726-5479) provides an advanced forum for the science and technology of physical, chemical sensors and biosensors. It publishes state-of-the-art reviews, regular research and application specific papers, short notes, letters to Editor and sensors related books reviews as well as academic, practical and commercial information of interest to its readership. Because it is an open access, peer review international journal, papers rapidly published in Sensors & Transducers Journal will receive a very high publicity. The journal is published monthly as twelve issues per annual by International Frequency Association (IFSA). In additional, some special sponsored and conference issues published annually. Sensors & Transducers Journal is indexed and abstracted very quickly by Chemical Abstracts, IndexCopernicus Journals Master List, Open J-Gate, Google Scholar, etc.

Topics Covered

Contributions are invited on all aspects of research, development and application of the science and technology of sensors, transducers and sensor instrumentations. Topics include, but are not restricted to:

- Physical, chemical and biosensors;
- Digital, frequency, period, duty-cycle, time interval, PWM, pulse number output sensors and transducers;
- Theory, principles, effects, design, standardization and modeling;
- Smart sensors and systems;
- · Sensor instrumentation;
- Virtual instruments;
- · Sensors interfaces, buses and networks;
- Signal processing;
- Frequency (period, duty-cycle)-to-digital converters, ADC;
- · Technologies and materials;
- Nanosensors;
- · Microsystems;
- Applications.

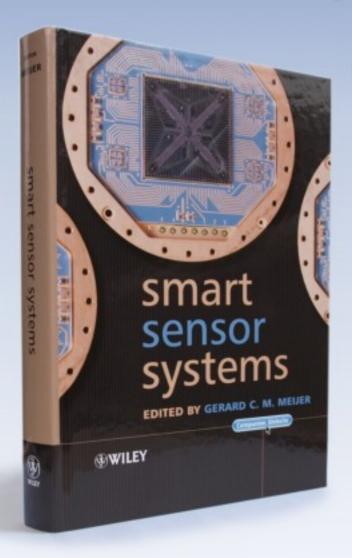
Submission of papers

Articles should be written in English. Authors are invited to submit by e-mail editor@sensorsportal.com 8-14 pages article (including abstract, illustrations (color or grayscale), photos and references) in both: MS Word (doc) and Acrobat (pdf) formats. Detailed preparation instructions, paper example and template of manuscript are available from the journal's webpage: http://www.sensorsportal.com/HTML/DIGEST/Submition.htm Authors must follow the instructions strictly when submitting their manuscripts.

Advertising Information

Advertising orders and enquires may be sent to sales@sensorsportal.com Please download also our media kit: http://www.sensorsportal.com/DOWNLOADS/Media_Kit_2009.pdf





'Written by an internationallyrecognized team of experts,
this book reviews recent developments in the field of
smart sensors systems, providing complete coverage
of all important systems aspects. It takes a multidisciplinary approach to the understanding, design and use of
smart semsor systems, their
building blocks and methods
of signal processing.'







Order online:

http://www.sensorsportal.com/HTML/BOOKSTORE/Smart_Sensor_Systems.htm

www.sensorsportal.com